

 $UHH \cdot ZMAW \cdot IfM \cdot Bundesstraße \ 53 \cdot D\text{--}20146 \ Hamburg$

Zentrum für Marine und Atmosphärische Wissenschaften Institut für Meereskunde Regional Dr. John Mortensen



November 29. 2004

Cruise Report LANCE 2004/15

Ship:	RV LANCE				
Cruise:	no. 15/2004				
Dates:	September 20 th – October 12 th 2004				
Port Calls:	Tromsø/Norway and Tromsø/Norway				
Institute:	Institut für Meereskunde, Universität Hamburg				
Scientific crew:	10				
Chief Scientist:	John Mortensen				
Principal Project:	SFB 512 E2 (The East Greenland Current, an indicator of the low frequency variability of the outflow of the Arctic Ocean/Nordic Seas system)				
Research area:	Greenland Sea				
Working Time Zone:	UTC				
Master:	Frits R. Johansen				

Participants:

Name	Speciality	Institute
Mortensen, John, Dr.	Chief Scientist	IfM HH
Drübbisch, Ulrich	Mooring	IfM HH
Glessmer, Mirjam	CTD	IfM HH
Karlsen, Tor Ivan	CTD	NPI
Majer, Claudia	CTD	IfM HH
Rolle, Kirstin	CTD	IfM HH
Rousset, Clément	CTD	LODYC
Verch, Norbert	CTD	IfM HH
Welsch, Andreas	Mooring	IfM HH
Yemenis, Theodoros, Dr.	CTD	IfM HH

IfM HH

Institut für Meereskunde Hamburg, Universität Hamburg, Bundesstr. 53, D-20146 Hamburg, Germany, e-mail: meincke@ifm.uni-hamburg.de, mortense@ifm.uni-hamburg.de

LODYC

Laboratoire d'Oceanographie Dynamicque et de Climatologie, UMR CNRS/IRD/UNIVER-SITET PIERRE ET MARIE CURIE, Universite Paris 6, Tour 45 5eme etage, Case 100, 4 place Jussieu, 75252 Paris CEDEX 05, France, email: Marie-Noelle.Houssais@lodyc.jussieu.fr, crlod@lodyc.jussieu.fr

NPI

Norsk Polarinstitut, Polarmiljøsenteret, N-9296 Tromsø, Norway, Email: mikelborg@npolar.no

Scientific Objectives

The RV LANCE 15/2004 cruise (The East Greenland Current, an indicator of the low frequency variability of the outflow of the system Arctic Ocean/Nordic Seas) was conducted by the *Institut für Meereskunde, Universität Hamburg* with the main objective of collecting hydrographic observations on the East Greenland continental shelf and slope in the Greenland Sea as part of the German project SFB 512, E2. The main goal of SFB 512, E2, is to understand how changes in the outflows of the Arctic Ocean/Nordic Seas system correlate with measured changes in the East Greenland Current. The LANCE 15/2004 cruise had the following aims:

- 1. to carry out hydrographic investigations on the East Greenland continental shelf and slope in the Greenland Sea. The investigation included CTD-casts (a Sea-Bird 911 plus CTD, titanium, was used during the cruise in combination with a SeaBird carousel 12 bottle water sampler).
- 2. to search for 3 deep sea moorings (HH1, HH3 and HH5) on the 74°N mooring section which were deployed in 2002 and not recovered in 2003.

- 3. to service two tube moorings (in Tube10 and Tube14; out Tube18 and Tube19) and an ADCP (Acoustic Doppler Current Profiler) mooring on the East Greenland shelf.
- 4. to deploy two new deep sea moorings (HH3 and HH5) as a replacement for the deep sea moorings (HH1, HH3 and HH5) deployed in 2002 and not found in 2003.
- 5. to collect underway ship-borne ADCP data (150kHz) along hydrographic transects.
- 6. to deploy 5 APEX-floats in the central part of the Greenland Sea.

Narrative of the cruise

The scientific parties from Germany and France arrived according to schedule at Tromsø, Norway, in the afternoon of Sunday September 19th. The scientific equipment was loaded, installed and made sea safe by late Monday afternoon, September 20th. RV Lance left the port of Tromsø Monday evening, September 20th at 1800 UTC (2000 hours local time). Course was set for the site where the Tube and ADCP moorings were located on the East Greenland continental shelf. Estimated time of arrival (ETA) was set to Thursday morning, September 23rd.

The working site was first reached Friday afternoon, September 24th, due to unfavourable weather. The ADCP-2003 mooring was successfully brought on deck that day in late afternoon by dredging taking place in a treacherous double swell. Further mooring work was postponed to the next morning due to the progressing darkness and heavy swells. During the evening a test and a microcat calibration CTD station were successfully occupied. Mooring work was commenced the next morning, Saturday September 25th, with the deployment of the ADCP-2004 mooring at 1126 UTC. In the critical phase of the deployment of the ADCP-2004 releaser problems were experienced, so the ADCP had to be brought down to the bottom twice. In the afternoon Tube 14 was recovered without problem at 1348 UTC and its replacement Tube 19 was deployed at 1657 UTC. The evening was used for a microcat calibration CTD station and a sonar search for Tube 10 which was deployed in 2002 and not recovered in 2003. The result of the search turned out negative. A search for a usable deployment site for Tube 18 was finished just before midnight when weather stopped further work.

Work was first resumed Monday morning, September 27th, with the assembly of Tube 18 on deck, which then was subsequently successfully deployed at 1408 UTC. A sonar search on Tube 18 revealed that the noise from the surface layer overrides return signals from the Tube completely. Opposite by passing directly over the Tube it was clearly seen on the echosounder. Course was now set for the deep sea mooring site HH5 where a combined sonar/releaser search was performed later that afternoon and in the early evening without any contact. During the night an echosounder/depth search was performed on the new HH5 mooring site. The morning of Tuesday September 28th was used to prepare the equipment for the deployment of two new deep sea moorings HH5 and HH3 in the afternoon. During the same time a CTD station was occupied to check the performance of the echosounder. The weight of the HH5-04 mooring was sent off at 1431 UTC and the first floats were observed to go down. After having waited for some time for the last float/instrument package on the line to sink it became obvious that it would not sink. Somewhere in the working process different rope lengths had been mixed up. Three floating instrument/float packages were taken in before tension on the rope was experienced and the rope cut leaving one instrument package in the abyss. Consulting the ship for spare weight parts it was decided to recover and redeploy the HH5-04 mooring the next day. The approaching darkness made further mooring work impossible and the evening was used for a sonar search for the HH3-02 mooring, an echosounder calibration CTD station and a search for a proper site to deploy the new HH3-04 mooring. As with the search for HH5-02 the outcome of the search for HH3-02 had the same negative result.

Wednesday September 29th started with the deployment of mooring HH3-04, and the operation ended at 1152 UTC. Mooring HH5-04 was then recovered at 1448 UTC in order to be redeployed at around 1900 UTC in the growing dark. The mooring was clearly seen in a subsequent sonar search, confirming the ability of sonar to detect conventional moorings. After finishing up almost all planned mooring work during the cruise, course was set for the first CTD station on the 74°N section (74°N; 10°W). ETA was set to 0400 UTC the next morning.

CTD work started at 0410 UTC Thursday morning, September 30th, and continued through the entire day. In the night between Thursday and Friday a combined sonar/releaser search for the HH1-02 mooring was performed without result. After the search, CTD work along the 74°N section was commenced and the section was ended near Greenland at 0912 UTC Saturday morning October 2nd.

With an approaching low-pressure system (a former tropical storm) and with less good ice conditions at the coast, course was set for weather shelter in Young Sound near Daneborg. When the elements were fighting at the coast a short unofficial visit to Daneborg was made Saturday afternoon. Not until Monday afternoon, October 4th, had the weather conditions improved enough that it was decided to leave the weather shelter at 1600 UTC. With a reasonable weather forecast RV Lance left the Young Sound and Daneborg at 1545 UTC saying good bye and good frost to the station. During the steam to the first CTD station on the 74°30'N section it was observed that locally formed sea ice had started to build, not observed two days before. The freezing season had started. The first CTD station (74°30'N; 18°17'W) on the 74°30'N section was started at 2135 UTC and ice was observed on the two first stations of the section. Loosing the damping effect of the ice cover and heading into stronger wind made the wave field grow so work had to be stopped at 0400 UTC Tuesday morning October 5th.

The rest of Tuesday October 5th was used for heading into the wind/sea. CTD work was not resumed until just after midnight at 0015 UTC Wednesday October 6th. Though swells were a disturbing factor in the beginning of the day work continued and the 74°30'N section was finished at 0705 UTC Thursday morning October 7th. The cruise was now running short of time and with the unstable weather conditions experienced up to now, course was set for the APEX floats deployment site in the central part of the Greenland Sea. After a steam of about 12 hours the first float of five was deployed without problem at 2145 UTC following a preceding CTD station. The last float was deployed Friday afternoon October 8th at 1718 UTC. Course was then set for Tromsø which was arrived after a rolling transit Sunday evening October 10th at 1900 CET (1700 UTC).

CTD (SBE 911plus CTD system) Sensor Status

Sensor	Serial no.	Calibration date
Temperature	4022	31.Mar. 2004
Conductivity	2433	08.Apr. 2004
Pressure	86555	17.Jul. 2001

For the control of the temperature and pressure SIS GmbH digital reversing thermometers and pressure sensor, RTM4002X and RPM6000X were applied. Additionally a Benthos Altimeter Model PSA-916 was mounted on the carousel.

Preliminary Results

CTD (Conductivity, Temperature and Depth) profiles were obtained along two east-west sections along 74°N and 74°30'N. Both sections had end points near the coast of East Greenland and in the deep part of the Greenland Sea Gyre, thus crossing the East Greenland Current. For the locations of sections and stations see Figure 1 and the list of stations below. Weather and limited cruise time made it impossible to occupy the 75°N section as in year 2002 and 2003. The evaluation of the hydrographic data given below is based on a preliminary data set. Therefore, post-cruise calibration might result in minor changes.

Potential temperature and salinity sections for 74°N and 74°30'N are shown below in Figure 2 and Figure 3, respectively. In the lower Figure of Figure 2 a water mass classification has been introduced to illustrate the distribution of water masses along these sections. The classification is also used in Figure 4 and Figure 5 and is an adjusted form of the classification suggested by Rudels et al. (2002).

The changes we have made with respect to the water mass classification of Rudels et al. (2002) are the following:

We distinguish between two types of Polar water, which mainly are found over the East Greenland continental shelf and upper part of the slope in the area in question. Polar Water (PW) is associated with water found in the temperature minimum layer observed clearly in Figure 5. Above we usually find a fresher and warmer water mass, which we refer to as the Polar Surface Water (PSW). One important result from the deployment of the Tube moorings is that these two water masses merge during winter (see Figure 6); by doing so the way is open for the creation of the coldest and most saline PW to leave the Polar and East Greenland Current area. An example of this extreme PW was observed in year 2002 (Figure 5). Weaker evidence of its presence was also observed in years 2003 and 2004.

At the surface in the deeper part of the Greenland Sea we find a warm and relatively saline water mass in September which we will refer to as Greenland Sea Arctic Surface Water (GS-ASW), and not as in the case of Rudels et al. (2002) as Polar Surface Water warm. We here stress that GS-ASW is found to the east of the Polar Front and therefore lies in the Arctic domain according to Swift and Aagaard (1981). Immediately below the cold PW is not found, but rather a more saline water mass of Atlantic or Arctic origin. The difference between PSW and GS-ASW is shown in Figure 5 where the 5 m properties (coloured points) are observed to fall into two distinct groups.

Below the PW and overlying the bottom of the East Greenland continental shelf we find another water mass, which we will refer to as East Greenland Shelf Bottom Water (EGS-BW) (Figure 4). The water mass is observed as a near bottom temperature maximum with salinity very similar to those observed in the lower part of the Re-circulating Atlantic Water (RAW) observed over the slope. The observations from this year suggest that the major contributor to this water mass is RAW which has entered the shelf further to the north of the 74°N section (see Figure 3). At 74°N the EGS-BW is in the process of getting mixed with the above lying PW. With decreasing bottom depth the bottom water becomes increasingly influenced by PW and with water properties observed to lie on the mixing line between PW and EGS-BW. Water with these properties has by Rudels et al. (2002) been categorized as Polar Intermediate Water (PIW). We will here point out that the so-called PIW not only derives from the colder parts of the Arctic Ocean thermocline as suggested by Rudels et al. (2002) but is also formed over the East Greenland continental shelf. Or more broadly just where PW overlies a warmer water mass.

We have replaced Arctic Intermediate Water (AIW) with Greenland Sea – AIW (GS-AIW) to avoid a mix up with similar water masses introduced in the Iceland Sea.

The last water mass to be introduce here is termed upper Greenland Sea Arctic Intermediate Water (uGS-AIW) and is similar to the one introduced in the Iceland Sea by Swift (1980) and Swift and Aagaard (1981) (see Figure 4), a convectively formed water mass limited to the near surface layer by salinity and underlying density gradients in the area and observed as a near surface temperature minimum.

Other preliminary findings are the following:

The winter cooling of the surface layer was in an early stage and the low temperatures in the surface layer of the inner stations on section 74°N were likely accomplished by transport of ice from the North Pole (Figure 5). In the deeper part of the research area the surface layer was still observed to be warm and even more saline than the two previous years. Also shown in Figure 5 is the condition observed in 2002 and 2003.

The core values of the RAW were very high (S>35.00 and T>3°C) this year and found over the upper reach of the continental slope at the 74°N section and outer reach of the continental slope at the 74°30'N section. In 2003 the core of the RAW was found at the outer reach of the continental slope at the 74°N section.

To state how much the share of a section occupied by a certain water mass had changed during a certain time span is not straightforward in this area and can often give rise to a lot of confusion. Let us give an example using a water mass found in Fram Strait, Atlantic Water (AW) (defined with T>2°C and S>34.92). We find that the share of the 74°N section occupied by AW in 2004 is 400% greater than measured in 2002. If the temperature and salinity limits are used on their own we find 119% and 25% respectively. This is huge difference we leave the readers to speculate over.

The share of PW over the continental shelf along the 74°N section seems to have decreased between 2002 and 2004.

The general temperature trend in the upper 500 m on the 74°N stations outside the RAW core between 2002 and 2004 was towards higher temperatures on the station nearest to Greenland and towards lower temperatures on the station in the interior of the Greenland Sea. In between there were hardly any observed changes.

Ice was observed in a few instances during the cruise and then near to the coast of East Greenland. On the 74°N section multi year ice was met in a narrow belt near the coast of East Greenland; its approximate location can be deduced from Figure 5 by the very low surface temperatures at a few stations. Inside the belt almost ice free conditions were met with: only a few scattered and likely grounded icebergs were observed. There were no signs of newly formed ice. A few days later on the 74°30'N section a mixture of new ice and ice of northern origin was observed in a belt from the coast and out to a position between the second and third CTD station. The remaining working area was ice free and only very few icebergs were encountered here.

Figure 6 shows TS-diagrams showing the property changes experienced by the upper instrument of Tube 14 in the depth range 16m to 30m (based on a preliminary data set). The undisturbed measuring depth was app. 16m and excursions to greater depths can be mainly related to increased currents. Some statistics are given in Table 1 and 2. At the time of the deployment of Tube 14 winter cooling had already started and temperatures were observed near to the freezing point; however, salinities were near to those observed during the end of the warm summer months. We believe that the subsequent increase in salinity along the freezing point curve is caused by the new ice formation, though changes related to frontal movements cannot be ruled out, but are likely of minor importance. More obvious horizontal/frontal movements were observed in April and May 2004 (Figure 6). At the same time the number of observations with depth greater than 30m were observed to increase.

In the period January to March 2004 we observed very small property changes. The water mass present in this period is the coldest and most saline version of PW briefly mentioned above. The beginning of the summer heating season was first observed in the end of May where temperatures start to leave near freezing conditions. As mentioned above, the high temperatures observed in April and May are likely connected to horizontal movements. Maximum temperature was found in September $(2.11^{\circ}C)$.

Table 1 shows that the percentage of excursion to depths greater than 30m were significant lower in the three summer months June to August 2004 than rest of the year and that significantly higher values were found in November 2003 and April 2004. Table 2 shows that for the deployment period of Tube 14 positive temperatures were only found in 5 out of 12 months and of all observations greater than 0°C, 58.23% of them were found in September.

Table 3 shows that there is a general increase in the percentage of observations observed in depths greater than 30m over the years. If this reflects a general increase of the mean current or an eventual decrease in buoyancy of the flotation still remains to be checked against the ADCP measurements made during two periods (Sep01-Sep02 and Oct03-Sep04). Related to this issue are the findings of Table 4 which shows a decrease of the numbers of positive temperature observations during the years.

Table 1. Percentage of depth observations greater than 30 dbar (\sim m) observed in a month by the upper instrument in Tube 14 (October 5th 2003 to September 25th 2004).

Oct03	Nov03	Dec03	Jan04	Feb04	Mar04
18.28	53.24	17.65	25.85	33.19	22.18
Apr04	May04	Jun04	Jul04	Aug04	Sep04
59.44	31.59	7.36	0.78	5.51	29.03

Table 2. Percentage of temperature observations greater than 0° C in the depth range 16m to 30m observer in a month by the upper instrument in Tube 14 (October 5th 2003 to September 25th 2004).

May04	Jun04	Jul04	Aug04	Sep04
3.5	10.4	6.8	5.7	59.1

Table 3. Percentage of depth observations greater than 30 dbar observed by the upper instrument during three different Tube deployments (deployments and recoveries usually took place in late September) in the same location.

Tube 6	2001/2002	8.50%
Tube 9	2002/2003	12.86%
Tube14	2003/2004	25.20%

Table 4. Percentage (or hours) of temperature observations greater than 0°C in water shallower than 30 dbar observed by the upper instrument during three different Tube deployments (deployments and recoveries usually took place in late September) in the same location.

Tube 6	2001/2002	7.89%	647 hours
Tube 9	2002/2003	6.24%	493 hours
Tube 14	2003/2004	6.64%	424 hours

References

Rudels. B., E. Fahrbach, J. Meincke, G. Budéus and P. Eriksson, The East Greenland Current and its contribution to the Denmark Strait overflow, ICES J. Mar. Sci., 59, 1133-1154, 2002.

Swift, J.H., Seasonal processes in the Iceland Sea, Ph.D. Thesis, University of Washington, 296 pp, 1980.

Swift, J.H., and K. Aagaard, Seasonal transitions and water mass formation in the Iceland and Greenland Seas, Deep-Sea Res., 20A(10): 1107-1129, 1981.

Further Remarks

We would like to thank Captain Johansen and his crew of RV Lance for good seamanship and cooperation during the cruise. We also send our regards to the personnel at the Greenland Commando and those we meet at Daneborg. Financial support came from the Deutsche Forschungsgemein-schaft (SFB 512), Bonn.

Figures

Figure 1. Position of the RV Lance sections and stations occupied in September/October 2004.

Figure 2. Potential temperature (upper) and salinity (lower) distribution along the 74°N section in September/October 2004. The water mass distribution is schematic shown in the lower Figure. Polar Surface Water/Polar Water (PSW/PW), East Greenland Shelf Bottom Water (EGS-BW), Re-circulating Atlantic Water (RAW), upper Polar Deep Water (uPDW), Greenland Sea Arctic

Intermediate Water (GS-AIW), Canadian Basin Deep Water (CBDW), Euasian Basin Deep Water (EBDW) and Greenland Sea Deep Water (GSDW).

Figure 3. Potential temperature (upper) and salinity (lower) distribution along the 74°30'N section in October 2004.

Figure 4. TS-diagrams for the 74°N section, September/October 2004 (upper and lower). The water mass distribution is schematic shown in the both Figures. Polar Water (PW) ,Greenland Sea Arctic Surface Water (GS-ASW), East Greenland Shelf Bottom Water (EGS-BW), Recirculating Atlantic Water (RAW), upper Greenland Sea Arctic Intermediate Water (uGS-AIW), upper Polar Deep Water (uPDW), Greenland Sea Arctic Intermediate Water (GS-AIW), Canadian Basin Deep Water (CBDW), Euasian Basin Deep Water (EBDW) and Greenland Sea Deep Water (GSDW). Only every third data point are shown. Blue and red curve are the profile of st. 21 (74°N, 10°W) and st. 79 (75°N, 1°W) respectively. For values of isopycnals used see Rudels et al. (2002).

Figure 5. TS-diagrams for the 74°N section, September/October 2004 (30/9-2/10) (upper left), October 2003 (5/10-7/10 and 12/10-13/10) (upper right) and September 2002 (19.9-24.9) (lower left). Also shown is the five meter values of each station (green points for 2002, 2004, red points for (5/10-7/10) 2003 and blue points for (12/10-13/10) 2003. The surface water mass distribution is schematic shown. Polar Surface Water (PSW), Polar Water (PW) and Greenland Sea Arctic Surface Water (GS-ASW). Only every third data point are shown. Also shown is the freezing point curve.

Figure 6. TS-diagrams showing the property changes experienced by the upper instrument (microcat) of Tube 14 in the depth range 16m to 30m. The undisturbed measuring depth was app. 16 m. The microcat time series have been divided into a monthly colour coding. Also shown is the freezing point curve.

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Mooring	Latitude	Water	Date	Instrument	Serial	Instr.
	Longitude	depth	and time	Туре	Number	Depth
		(m)	of first			(m)
			record			
HH1	74°04.565N	2771	02.10.02	RCM 4	2022	109
	12°46.893W			SBE 16	2411	110
				SBE 37	1390	165
				RCM 5	8414	241
				SBE 37	1391	242
				SBE 37	1395	455
				RCM 8	9876	667
				SBE 37	1597	668
				RCM 8	9875	1195
				SBE 16	3023	1196
				RT 161 BS	874	1723
HH3	74°00.791N	2190	01.10.02	RCM 7	11286	74
	13°53.523W			SBE 16	2410	75
				SBE 37	1396	131
				RCM 8	9841	187
				SBE 37	1392	188
				RCM 5	6855	401
			1		1001	100

Record Length

(days)

1)

1)

Table 5. Mooring recoveries during Lance 2004/15MooringLatitudeWaterDateInstruction

				RCM 5	6855	401	
				SBE 37	1394	402	
				RCM 5	8416	615	
				SBE 37	1397	616	
				RCM 8	9221	1142	
				SBE 16	2409	1143	
				RT 661 B1S	376	1670	
HH5	74°01.950N	1350	01.10.02	RCM 4	209	65	1)
	14°39.215W			SBE 16	2408	66	
				THM-R	1334	67-	
				THM-CH	1277	-118	
				SBE 37	1914	121	
				RCM 4	204	176	
				SBE 37	0066	177	
				SBE 37	1885	232	
				RCM 7	11271	339	
				SBE 37	1594	340	
				RCM 5	8415	552	
				SBE 37 P	1400	553	
				RCM 8	9203	818	
				SBE 37	1393	819	
				RT 661 B1S	372	1339	
Tube10	74°03.93N	202	21.09.02	SBE 37 P	1690	15	1)
	15°45.05W			SBE 37	1598	55	
				AR 661 B1S	613	198	

1) Mooring or Tube could not be recovered during the RV Lance 2004 cruise.

Table 5. Continued

Mooring	Latitude	Water	Date	Instrument	Serial	Instr.	Record
	Longitude	depth	and time	Туре	Number	Depth	Length
		(m)	of first			(m)	(days)
			record				
ADCP	74°02.782N	199	08.10.03	RDI ADCP	585	199	355
	15°38.290W			153 kHz			
Tube 14	74°01.660N	346	05.10.03	SBE37 P	2803	16	357
	15°31.366W			SBE 37	2935	56	
				AR 861 B1S	207	341	

Mooring	Latitude	Water	Date	Instrument	Serial	Instr.	Record
U U	Longitude	depth	and time	Туре	Number	Depth	Length
	C	(m)	of first			(m)	(days)
			record				
ADCP	74°02.645N	202	25.09.04	RDI ADCP	603	202	
	15°38.127W			153 kHz			
Tube 19	74°01.648N	341.5	25.09.04	SBE 37 P	2967	20	
	15°31.513W			SBE 37	2942	60	
				AR 861 B1S	209	337	
Tube 18	74°04.339N	200	27.09.04	SBE 37 P	1399	20	
	15°47.315W			SBE 37	2937	60	
				AR 861 B1S	210	197	
HH3-04	73°59.979N	2088	29.09.04	SBE 16	2407	100	
	14°02.463W			RCM 8	12301	100	
				SBE 37 P	2804	250	
				RCM 7	11297	250	
				SBE 37	2940	500	
				RCM 8	9815	500	
				SBE 37 P	1401	750	
				RCM 11	81	750	
				SBE 16	3024	1000	
				RCM 11	171	1000	
				RT 661 B1S	200	1600	
HH5-04	73°59.891N	1188	29.09.04	SBE 16	2412	100	
	15°00.240W			RCM 8	12303	100	
				SBE 37 P	2863	250	
				RCM 7	11294	250	
				SBE 37	2941	500	
				RCM 7	11295	500	
				SBE 16	3025	750	
				RCM 9 OP	1025	750	
				AR 861 B1S	206	980	

Table 6. Mooring deployments during Lance 2004/15

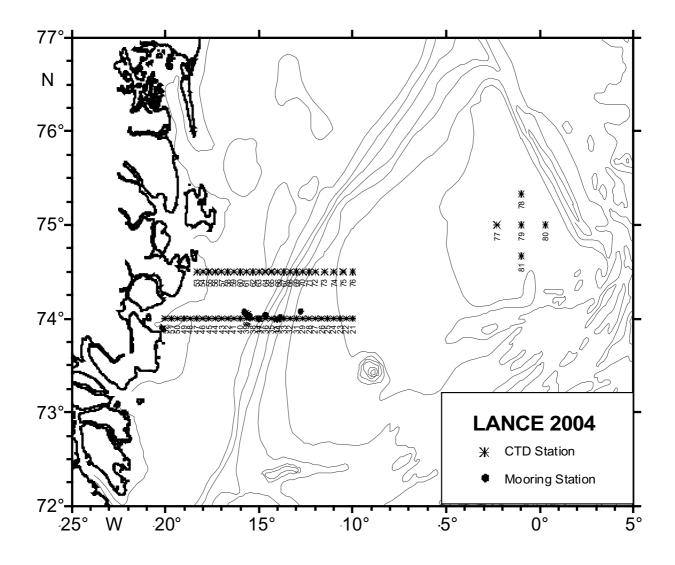
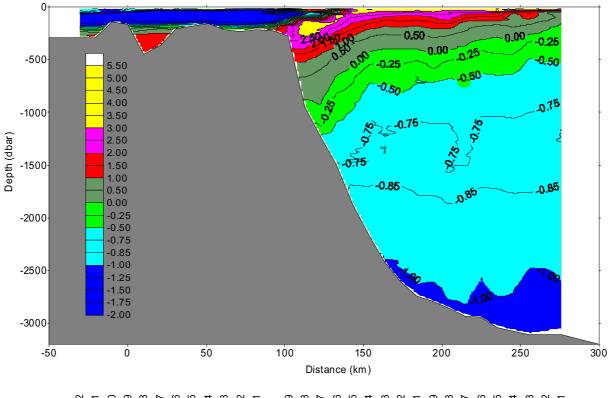
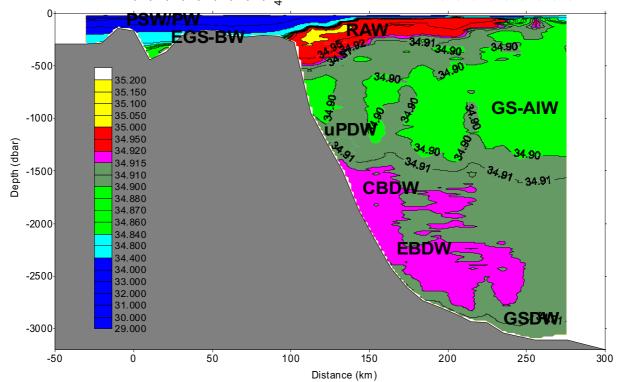


Figure 1. Position of the "Lance" sections and stations taken in September/October 2004.





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Figure 2. Potential temperature (upper) and salinity (lower) distribution along the 74°N section in September/October 2004. The water mass distribution is schematic shown in the lower Figure. Polar Surface Water/Polar Water (PSW/PW), East Greenland Shelf Bottom Water (EGS-BW), Re-circulating Atlantic Water (RAW), upper Polar Deep Water (uPDW), Greenland Sea Arctic Intermediate Water (GS-AIW), Canadian Basin Deep Water (CBDW), Euasian Basin Deep Water (EBDW) and Greenland Sea Deep Water (GSDW).

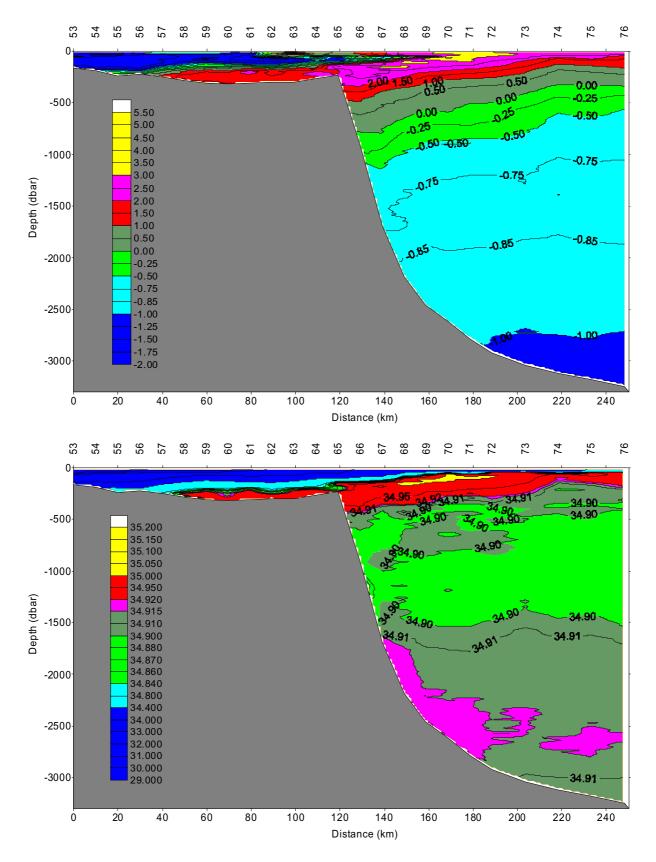


Figure 3. Potential temperature (upper) and salinity (lower) distribution along the 74°30'N section in October 2004.

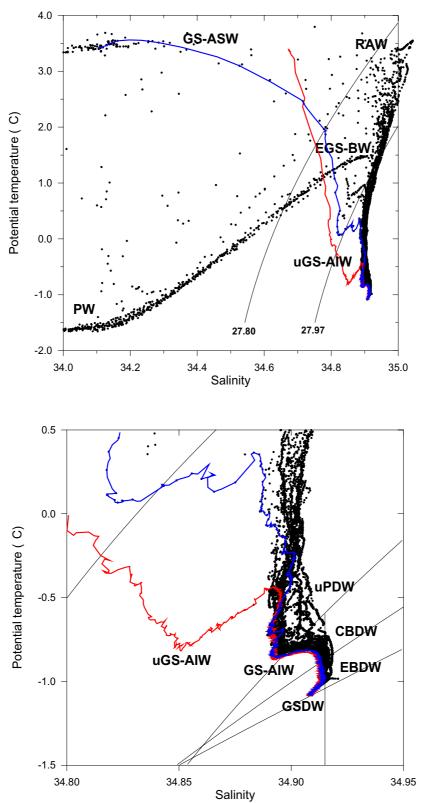


Figure 4. TS-diagrams for the 74°N section, September/October 2004 (upper and lower). The water mass distribution is schematic shown in the both Figures. Polar Water (PW), Greenland Sea Arctic Surface Water (GS-ASW), East Greenland Shelf Bottom Water (EGS-BW), Re-circulating Atlantic Water (RAW), upper Greenland Sea Arctic Intermediate Water (uGS-AIW), upper Polar Deep Water (uPDW), Greenland Sea Arctic Intermediate Water (GS-AIW), Canadian Basin Deep Water (CBDW), Euasian Basin Deep Water (EBDW) and Greenland Sea Deep Water (GSDW). Only every third data point are shown. Blue and red curve are the profile of st. 21 (74°N, 10°W) and st. 79 (75°N, 1°W) respectively. For values of isopycnals used see Rudels et al. (2002).

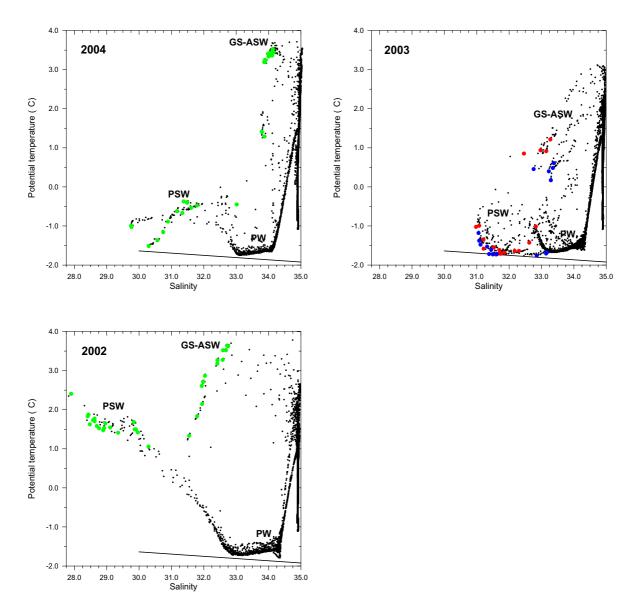


Figure 5. TS-diagrams for the 74°N section, September/October 2004 (30/9-2/10) (upper left), October 2003 (5/10-7/10 and 12/10-13/10) (upper right) and September 2002 (19.9-24.9) (lower left). Also shown is the five meter values of each station (green points for 2002, 2004, red points for (5/10-7/10) 2003 and blue points for (12/10-13/10) 2003. The surface water mass distribution is schematic shown. Polar Surface Water (PSW), Polar Water (PW) and Greenland Sea Arctic Surface Water (GS-ASW). Only every third data point are shown. Also shown is the freezing point curve.

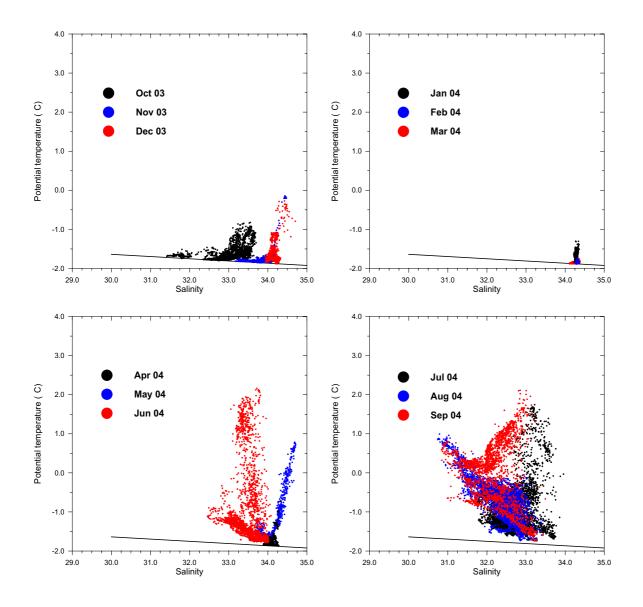


Figure 6. TS-diagrams showing the property changes experienced by the upper instrument (microcat) of Tube 14 in the depth range 16m to 30m. The undisturbed measuring depth was app. 16 m. The microcat time series have been divided into a monthly colour coding. Also shown is the freezing point curve.

List of stations

EXPO- CODE	Stat. No.	Cast No.	Cast Type	Date mmddyy	Time UTC	Code	Positi Latitude	on Longitude		ottom depth	Max Bottom Comments Press. Dist.
58LA1504 58LA1504	001 001	01 01	MOR MOR	092404 092404	1530 1533	BE EN	74 00.73 N 74 00.74 N		GPS GPS	528 524	Listening for Tube 14 contact
58LA1504 58LA1504	002 002	01 01	MOR MOR	092404 092404	1553 1813	BE EN	74 02.66 N 74 02.21 N		GPS GPS	207 189	Recovery of ADCP mooring 03
58LA1504 58LA1504 58LA1504	003 003 003	01 01 01	ROS/CTD ROS/CTD ROS/CTD	092404 092404 092404	1921 1933 1940	BE BO EN	74 03.01 N 74 02.96 N 74 02.92 N	15 36.99 W	GPS GPS GPS	219 211 211	205 7 Teststation
58LA1504 58LA1504 58LA1504	004 004 004	01 01 01	ROS/CTD ROS/CTD ROS/CTD	092404 092404 092404	2024 2031 2057	BE BO EN	74 02.97 N 74 02.97 N 74 02.99 N	15 35.12 W	GPS GPS GPS	222 226 231	103 126 Calibration of MICROCATS
58LA1504 58LA1504	005 005	01 01	MOR MOR	092504 092504	1040 1126	BE EN	74 02.55 N 74 02.65 N		GPS GPS	200 201	Deployment of ADCP mooring 04
58LA1504 58LA1504	006 006	01 01	MOR MOR	092504 092504	1248 1348	BE EN	74 01.75 N 74 01.49 N		GPS GPS	325 362	Recovery of Tube 14
58LA1504 58LA1504	007 007	01 01	MOR MOR	092504 092504	1631 1657	BE EN	74 01.53 N 74 01.65 N		GPS GPS	315 342	Deployment of Tube 19
58LA1504 58LA1504	008 008	01 01	ROS/CTD ROS/CTD	092504 092504	1900 1938	BE EN	74 03.70 N 74 05.50 N		GPS GPS	197 202	102 Calibration of MICROCATS
58LA1504 58LA1504	009 009	01 01	MOR MOR	092504 092504	1940 2100	BE EN	74 03.93 N 74 03.93 N		GPS GPS	202 202	Sonar search for Tube 10 negative
58LA1504 58LA1504	010 010	01 01	MOR MOR	092704 092704	1356 1408	BE EN	74 04.23 N 74 04.34 N		GPS GPS	199 200	Deployment of Tube 18
58LA1504 58LA1504	011 011	01 01	MOR MOR	092704 092704	1424 1439	BE EN	74 04.34 N 74 04.34 N		GPS GPS	200 200	Sonar search for Tube 18 Seen on Echo sounder
58LA1504 58LA1504	012 012	01 01	MOR MOR	092704 092704	1659 1805	BE EN	74 01.89 N 74 02.00 N		GPS GPS	1365 1356	Sonar search for Mooring HH5-02 negative
58LA1504 58LA1504	013 013	01 01	MOR MOR	092704 092704	1839 1847	BE EN	74 02.36 N 74 02.17 N		GPS GPS	1344 1354	Listening for Releaser of HH5-02 negative
58LA1504 58LA1504 58LA1504	014 014 014	01 01 01	ROS/CTD ROS/CTD ROS/CTD	092804 092804 092804	0923 0947 1012	BE BO EN	73 59.99 N 74 00.05 N 74 00.06 N	15 00.70 W	GPS GPS GPS	1185 1176 1174	Calibration of Echo sounder 1187 9
58LA1504 58LA1504	015 015	01 01	MOR MOR	092804 092804	1330 1547	BE EN	74 01.84 N 73 59.78 N		GPS GPS	1068 1210	Deployment of Mooring HH5-04 partly failed
58LA1504 58LA1504	016 016	01 01	MOR MOR	092804 092804	1826 1900	BE EN	74 00.79 N 74 00.79 N		GPS GPS	2191 2191	Sonar search for Mooring HH3-02 negative
58LA1504 58LA1504 58LA1504	017 017 017	01 01 01	ROS/CTD ROS/CTD ROS/CTD	092804 092804 092804	1947 2028 2110	BE BO EN	73 59.82 N 73 59.39 N 73 58.97 N	14 01.81 W	GPS GPS GPS	2106 2129 2130	Calibration of Echo sounder 2140 9
58LA1504 58LA1504	018 018	01 01	MOR MOR	092904 092904	0950 1152	BE EN	73 57.72 N 73 59.59 N		GPS GPS	2201 2120	Deployment Mooring HH3-04
58LA1504 58LA1504	019 019	01 01	MOR MOR	092904 092904	1343 1448	BE EN	74 00.10 N 73 59.76 N		GPS GPS	1172 1195	Recovery of Mooring HH5-04
58LA1504 58LA1504	020 020	01 01	MOR MOR	092904 092904	1807 1912	BE EN	73 58.54 N 73 59.60 N		GPS GPS	1309 1188	Redeployment of Mooring HH5-04 Sonar sweep positive
58LA1504 58LA1504 58LA1504	021 021 021	01 01 01	ROS/CTD ROS/CTD ROS/CTD	093004 093004 093004	0410 0515 0617	BE BO EN	74 00.01 N 73 59.96 N 73 59.84 N	10 02.61 W	GPS GPS GPS	3068 3068 3059	3054
58LA1504 58LA1504 58LA1504	022 022 022	01 01 01	ROS/CTD ROS/CTD ROS/CTD	093004 093004 093004	0655 0750 0839	BE BO EN	74 00.02 N 74 00.39 N 74 00.67 N		GPS GPS GPS	3036 3055 3063	3041
58LA1504 58LA1504 58LA1504	023 023 023	01 01 01	ROS/CTD ROS/CTD ROS/CTD	093004 093004 093004	0911 1005 1101	BE BO EN	74 00.12 N 74 00.28 N 74 00.42 N	10 43.36 W	GPS GPS GPS	3046 3042 3036	3099 8
58LA1504 58LA1504 58LA1504	024 024 024	01 01 01	ROS/CTD ROS/CTD ROS/CTD	093004 093004 093004	1133 1230 1328	BE BO EN	74 00.03 N 74 00.00 N 73 59.85 N	11 02.01 W	GPS GPS GPS	3014 3013 2999	3067 7
58LA1504 58LA1504 58LA1504	025 025 025	01 01 01	ROS/CTD ROS/CTD ROS/CTD	093004 093004 093004	1402 1502 1553	BE BO EN	73 59.96 N 73 59.92 N 74 00.00 N	11 21.69 W	GPS GPS GPS	2975 2966 2957	3027 10
58LA1504 58LA1504 58LA1504	026 026 026	01 01 01	ROS/CTD ROS/CTD ROS/CTD	093004 093004 093004	1632 1723 1814	BE BO EN	73 59.99 N 73 59.95 N 73 59.96 N	11 41.66 W	GPS GPS GPS	2884 2878 2876	2928 8
58LA1504 58LA1504 58LA1504	027 027 027	01 01 01	ROS/CTD ROS/CTD ROS/CTD	093004 093004 093004	1848 1942 2034	BE BO EN	74 00.05 N 74 00.27 N 74 00.54 N		GPS GPS GPS	2873 2869 2857	2918 9
58LA1504 58LA1504 58LA1504	028 028 028	01 01 01	ROS/CTD ROS/CTD ROS/CTD	093004 093004 093004	2109 2200 2238	BE BO EN	73 59.99 N 74 00.28 N 74 00.69 N		GPS GPS GPS	2805 2803 2805	2848 10
58LA1504 58LA1504 58LA1504	029 029 029	01 01 01	ROS/CTD ROS/CTD ROS/CTD	093004 100104 100104	2323 0014 0105	BE BO EN	74 00.02 N 74 00.38 N 74 00.64 N		GPS GPS GPS	2745 2759 2758	2784 9
58LA1504 58LA1504	030 030	01 01	MOR MOR	100104 100104	0130 0240	BE EN	74 04.57 N 74 04.57 N	12 46.89 W 12 46.89 W	GPS GPS	2771 2771	Sonar search and listening for Mooring HH1-02 negative
58LA1504 58LA1504 58LA1504	031 031 031	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100104 100104 100104	0329 0421 0508	BE BO EN	74 00.26 N	13 00.05 W 13 00.02 W 13 00.26 W	GPS GPS GPS	2686 2687 2687	2726 8
58LA1504 58LA1504 58LA1504	032 032 032	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100104 100104 100104	0547 0635 0720	BE BO EN	74 00.09 N	13 19.97 W 13 19.15 W 13 18.08 W	GPS GPS GPS	2558 2565 2575	2595 10

58LA1504 58LA1504	033 033	01 01	ROS/CTD ROS/CTD		0804 0847	BE BO		59.89 N 59.13 N				GPS GPS	2379 2383	2409	8	
58LA1504 58LA1504 58LA1504	033 034 034	01 01 01	ROS/CTD ROS/CTD ROS/CTD		0928 1015 1053	EN BE BO	73	58.51 N 59.95 N 59.31 N	14	00.01	W	GPS GPS GPS	2396 2126 2149	2145	8	
58LA1504	034	01	ROS/CTD ROS/CTD	100104	1130	EN BE	73 73	58.86 N 59.96 N	14 14	01.29	W	GPS GPS	2149 2149 1844	2145		
58LA1504 58LA1504 58LA1504	035 035 036	01 01 01	ROS/CTD ROS/CTD ROS/CTD		1246 1323 1404	BO EN BE	73	59.91 N 59.96 N 00.08 N	14		W	GPS GPS GPS	1852 1861 1463	1865	9	
58LA1504 58LA1504 58LA1504	036 036 036	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100104	1435 1503	BO EN	73	59.75 N 59.58 N	14	39.62	W	GPS GPS GPS	1483 1487 1510	1484	9	
58LA1504 58LA1504 58LA1504	037 037 037	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100104 100104 100104	1548 1608 1632	BE BO EN	73	59.96 N 59.75 N 59.46 N	14	58.81	W	GPS GPS GPS	1202 1228 1261	1220	10	
58LA1504 58LA1504 58LA1504	038 038 038	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100104 100104 100104	1713 1729 1747	BE BO EN	73	00.03 N 59.87 N 59.67 N	15	19.70	W	GPS GPS GPS	934 949 963	937	8	
58LA1504 58LA1504 58LA1504	039 039 039	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100104 100104 100104	1847 1854 1902	BE BO EN	73	59.96 N 59.90 N 59.82 N	15	40.12	W	GPS GPS GPS	263 270 281	263	9	
58LA1504 58LA1504 58LA1504	040 040 040	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100104	1942 1947 2004	BE BO EN	73	59.91 N 59.79 N 59.60 N	16	00.48	W	GPS GPS GPS	221 221 221	212	pump 9	problems during down cast
58LA1504 58LA1504 58LA1504	041 041 041	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100104 100104 100104	2045 2052 2057	BE BO EN	73	00.00 N 59.98 N 59.92 N	16	20.41	W	GPS GPS GPS	208 211 207	201	7	
58LA1504 58LA1504 58LA1504	042 042 042	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100104 100104 100104	2145 2151 2157	BE BO EN	74	00.11 N 00.09 N 00.09 N	16	39.65	W	GPS GPS GPS	228 229 230	219	9	
58LA1504 58LA1504 58LA1504	043 043 043	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100104 100104 100104	2250 2256 2301	BE BO EN	74	00.00 N 00.00 N 00.00 N	16	59.90	W	GPS GPS GPS	213 210 209	204	8	
58LA1504 58LA1504 58LA1504	044 044 044	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100104	2353 2357 0002	BE BO EN	74	00.08 N 00.08 N 00.07 N	17	20.11	W	GPS GPS GPS	159 160 161	150	8	
58LA1504 58LA1504 58LA1504	045 045 045	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100204 100204 100204	0054 0100 0106	BE BO EN	74	00.03 N 00.00 N 59.98 N	17	40.23	W	GPS GPS GPS	176 176 176	169	8	
58LA1504 58LA1504 58LA1504	046 046 046	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100204 100204 100204	0152 0158 0204	BE BO EN	73	59.99 N 59.89 N 59.80 N	18	00.09	W	GPS GPS GPS	210 207 206	196	9	
58LA1504 58LA1504 58LA1504	047 047 047	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100204 100204 100204	0253 0301 0310	BE BO EN	73	00.04 N 59.99 N 59.94 N	18	19.98	W	GPS GPS GPS	362 365 365	354	9	
58LA1504 58LA1504 58LA1504	048 048 048	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100204 100204 100204	0357 0407 0417	BE BO EN	73	59.98 N 59.84 N 59.73 N	18	39.84	W	GPS GPS GPS	447 441 437	434	9	
58LA1504 58LA1504 58LA1504	049 049 049	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100204 100204 100204	0507 0512 0518	BE BO EN	73	59.96 N 59.85 N 59.73 N	19	00.09	W	GPS GPS GPS	169 166 170	154	10	
58LA1504 58LA1504 58LA1504	050 050 050	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100204 100204 100204	0627 0631 0637	BE BO EN	73	59.89 N 59.86 N 59.83 N	19	19.98	W	GPS GPS GPS	139 139 139	129	7	
58LA1504 58LA1504 58LA1504	051 051 051	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100204	0739 0746 0753	BE BO EN	74	00.05 N 00.00 N 59.91 N	19	40.07	W	GPS GPS GPS	287 288 286	277	9	
58LA1504 58LA1504 58LA1504	052 052 052	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100204	0903	BE BO EN	74	00.09 N 00.07 N 00.05 N	19	59.87	W	GPS	286 291 289	281	9	
58LA1504 58LA1504 58LA1504	053 053 053	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100404	2141	BE BO EN	74 74 74	30.05 N 30.01 N 30.01 N	18 18 18	17.38 17.21 17.04	W W W	GPS GPS GPS	169 167 164	156	9	
58LA1504 58LA1504 58LA1504	054 054 054	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100404	2242	BE BO EN	74	29.78 N 29.62 N 29.43 N	17	59.49	W	GPS	192 187 190	176	13	
58LA1504 58LA1504 58LA1504	055 055 055	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100404	2334	BE BO EN	74	30.00 N 29.91 N 29.82 N	17	40.02	W	GPS	235 239 241	227	7	
58LA1504 58LA1504 58LA1504	056 056 056	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100504	0029	BE BO EN	74	29.94 N 29.79 N 29.65 N	17	19.66	W	GPS	220 222 220	211	9	
58LA1504 58LA1504 58LA1504	057 057 057	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100504	0127	BE BO EN	74	29.95 N 29.79 N 29.63 N	16	59.82	W	GPS	248 250 250	241	9	
58LA1504 58LA1504 58LA1504	058 058 058	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100504	0223	BE BO EN	74	29.95 N 29.75 N 29.73 N	16	39.86	W	GPS	274 287 289	272	9	
58LA1504 58LA1504 58LA1504	059 059 059	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100504	0333	BE BO EN	74	29.98 N 29.84 N 29.80 N	16	19.95	W	GPS	310 308 307	299	10	
58LA1504 58LA1504 58LA1504	060 060 060	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100604	0023	BE BO EN	74	29.99 N 29.93 N 29.87 N	15	59.55	W	GPS	317 316 316	311	7	
58LA1504 58LA1504 58LA1504	061 061 061	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100604 100604 100604	0108 0118 0127	BE BO EN	74 74 74	30.02 N 29.86 N 29.67 N	15 15 15	39.93 39.57 39.29	W W W	GPS GPS GPS	302 307 308	299	5	

58LA1504 58LA1504 58LA1504	062 062 062	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100604 100604 100604	0204 0212 0218	BE BO EN	7	4 2	29.	90	Ν	15	19	.01 .72 .63	W	GPS GPS GPS	297 294 293	288	8
58LA1504 58LA1504 58LA1504	063 063 063	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100604 100604 100604	0256 0305 0313	BE BO EN	7	4 2	29.	02 95 97	Ν	14	59	.09 .96 .07	W	GPS GPS GPS	302 303 303	294	8
58LA1504 58LA1504 58LA1504	064 064 064	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100604 100604 100604	0352 0358 0404	BE BO EN	7	4 2	29.		N	14	39	.90 .96 .84	W	GPS GPS GPS	263 261 264	256	7
58LA1504 58LA1504 58LA1504	065 065 065	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100604 100604 100604	0442 0447 0454	BE BO EN	7	4 2	29.		Ν	14	19	.01 .84 .76	W	GPS GPS GPS	227 231 227	223	8
58LA1504 58LA1504 58LA1504	066 066 066	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100604 100604 100604	0535 0553 0610	BE BO EN	7	4 2	29.	98 82 72	Ν	13	59	.97 .59 .12	W	GPS GPS GPS	895 914 936	901	9
58LA1504 58LA1504 58LA1504	067 067 067	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100604 100604 100604	0649 0719 0745	BE BO EN	7	4 2	29.	92 52 11	Ν	13	41	.21 .08 .14	W	GPS GPS GPS	1680 1666 1667	1681	9
58LA1504 58LA1504 58LA1504	068 068 068	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100604 100604 100604	0843 0925 1006	BE BO EN	7	4 2	29.	95 31 72	N	13	21	.95 .20 .77	W	GPS GPS GPS	2154 2149 2133	2169	10
58LA1504 58LA1504 58LA1504	069 069 069	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100604 100604 100604	1056 1142 1228	BE BO EN	7	4 2	29.	93 67 30	Ν	13	00	.02 .83 .72	W	GPS GPS GPS	2419 2420 2428	2450	10
58LA1504 58LA1504 58LA1504	070 070 070	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100604 100604 100604	1307 1358 1446	BE BO EN	7	4 2	29.		Ν	12	41	.99 .22 .27	W	GPS GPS GPS	2570 2564 2552	2602	9
58LA1504 58LA1504 58LA1504	071 071 071	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100604 100604 100604	1531 1623 1706	BE BO EN	7	4 2	29.		Ν	12	21	.95 .23 .40	W	GPS GPS GPS	2734 2726 2717	2774	9
58LA1504 58LA1504 58LA1504	072 072 072	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100604 100604 100604	1749 1841 1930	BE BO EN	7	4 2	29.		Ν	12	00	.96 .34 .85	W	GPS GPS GPS	2862 2860 2866	2907	10
58LA1504 58LA1504	072 072	02 02	ROS/CTD ROS/CTD	100604 100604	1943 2015	BE EN								.67 .15		GPS GPS	2867 2869	152	Calibration of MICROCATS
58LA1504 58LA1504 58LA1504	073 073 073	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100604 100604 100604	2110 2200 2250	BE BO EN	7	4 3	30.		Ν	11	28	.01 .95 .59	W	GPS GPS GPS	2977 2979 2983	3028	10
58LA1504 58LA1504 58LA1504	074 074 074	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100604 100704 100704	2342 0040 0135	BE BO EN	7	4 3	30.	36	N	10	58	.88 .49 .55	W	GPS GPS GPS	3056 3057 3060	3109	9
58LA1504 58LA1504 58LA1504	075 075 075	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100704 100704 100704	0226 0321 0414	BE BO EN	7	4 3	30.	78	Ν	10	28	.94 .77 .44	W	GPS GPS GPS	3116 3118 3122	3171	10
58LA1504 58LA1504 58LA1504	076 076 076	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100704 100704 100704	0508 0609 0705	BE BO EN	7	4 3	30.	03 68 01	N	09	58	.04 .00 .27	W	GPS GPS GPS	3172 3178 3181	3236	8
58LA1504 58LA1504 58LA1504	077 077 077	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100704 100704 100704	1911 2023 2128	BE BO EN	7	4 5	59.	86 19 74	Ν	02	16	.66 .88 .09	W	GPS GPS GPS		3685	no Echosounder 10
58LA1504	077	02	FLOAT	100704	2145	DE	7	4 5	59.	97	Ν	02	17	.40	W	GPS			APEX Float No.1736
58LA1504 58LA1504 58LA1504	078 078 078	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100804 100804 100804	0049 0156 0259	BE BO EN	7	5 2	19.	93 48 89	Ν	00	58	.56 .31 .60	W	GPS GPS GPS		3755	no Echosounder 7
58LA1504	078	02	FLOAT	100804	0318	DE	7	5 3	19.	98	N	00	59	.86	W	GPS			APEX Float No.1737
58LA1504 58LA1504 58LA1504	079 079 079	01 01 01		100804 100804 100804		BE BO EN	7	4 5	59.	40	Ν	00	59	.89 .58 .07	W	GPS GPS GPS		3580	no Echosounder 10
58LA1504	079	02	FLOAT	100804	0739	DE	7	4 5	59.	95	N	01	00	.07	W	GPS			APEX Float No.1738
58LA1504 58LA1504 58LA1504	080 080 080	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100804 100804 100804		BE BO EN	7	4 5	59.	50	Ν	00	18	.45 .46 .07	Е	GPS GPS GPS		3734	no Echosounder 54 near end of cable
58LA1504	080	02	FLOAT	100804	1210	DE	7	5 (0.00	08	N	00	17	.67	Е	GPS			APEX Float No.1739
58LA1504 58LA1504 58LA1504	081 081 081	01 01 01	ROS/CTD ROS/CTD ROS/CTD	100804 100804 100804	1605	BE BO EN	7	4 3	39.	34	Ν	01	00	.95 .19 .33	W	GPS GPS GPS		3537	no Echosounder
58LA1504	081	02	FLOAT	100804	1718	DE	7	4 3	39.	97	N	00	59	.91	W	GPS			APEX Float No.1740